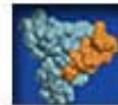
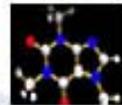
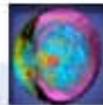




SciDAC

Scientific Discovery through Advanced Computing



Reliability/Resilience Panel

HEC File System & IO Workshop, Aug 3, 2010

Garth Gibson, Lin Xiao
Carnegie Mellon University



Carnegie Mellon
Parallel Data Laboratory



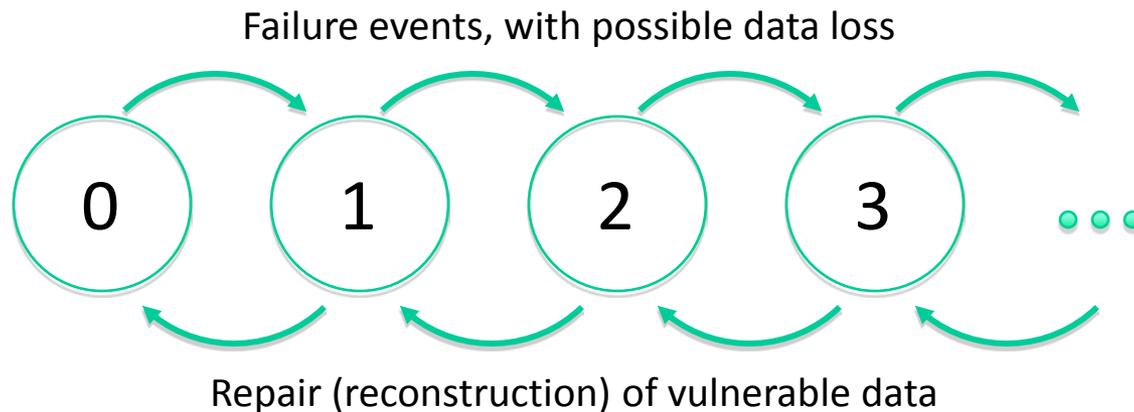
Metrics

- 1988: MTBF → MMTDL
- 2004 (Corbett): add RAID6 and a “correlated failures factor”
- $\text{Prob}(DL < dt) \propto dt / \text{MTTDL}$
 - Measurement equiv: Avg Data Loss Events / year
- But none of this is commonly used
- *Max simultaneous failures always tolerated (N+i)*
- Emphasize the illusion of perfection
- But probability of zero data loss approaches zero
 - Media errors, dependent failures, failed upgrades
 - A few lost files not the same as loss of millions or TBs
- Better, simple metrics: Avg Lost Bytes / year

$$MTTF_{RAID} = \frac{(MTTF_{Disk})^2}{(D+C*n_G)*(G+C-1)*MTTR}$$

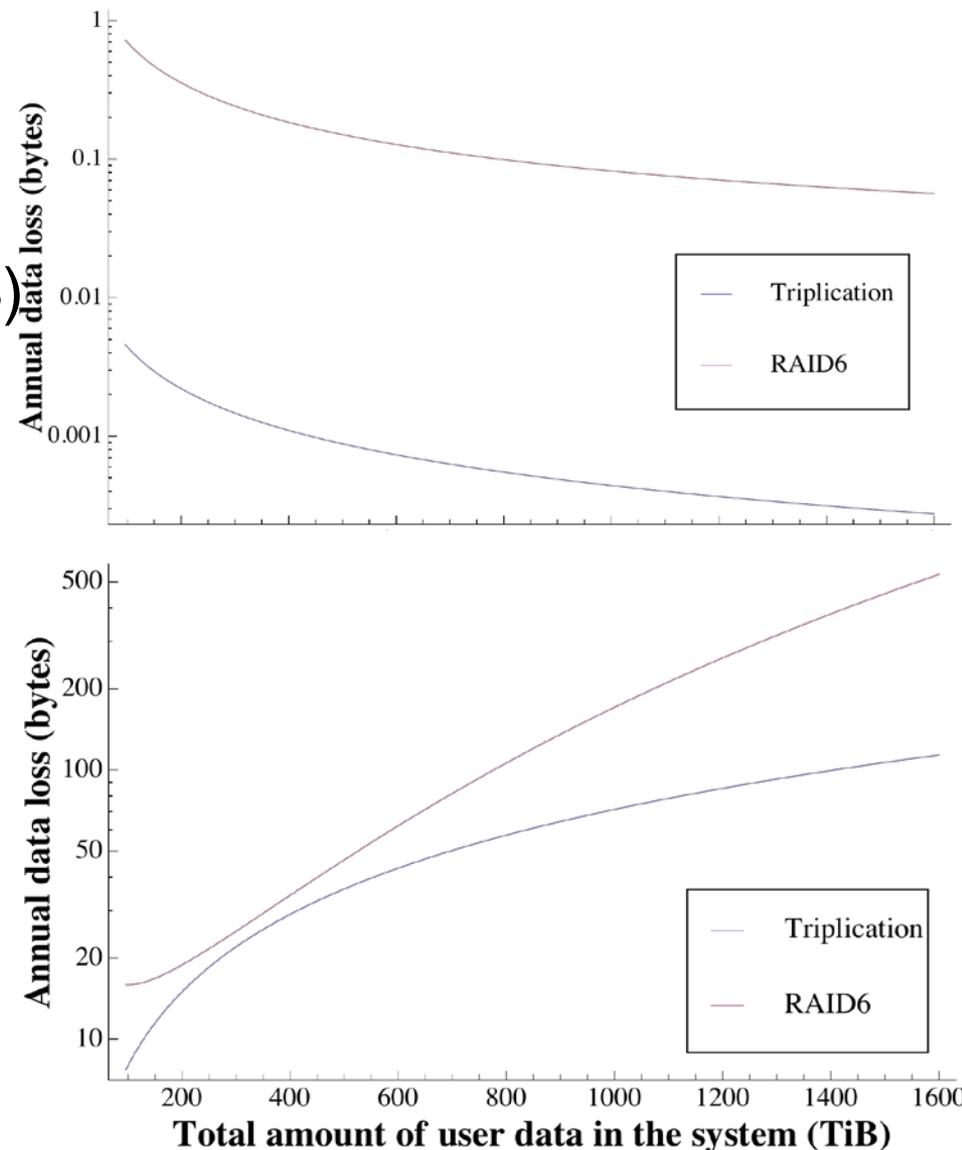
RAID 6 versus Triplication

- Model declustering / random replication
 - RAID 6 is cheaper, so triplication should be more reliable...
- Fundamental properties, not accurate distributions (ie., way too much Poisson), at least to start ...
- Simple Renewal Reward Markov model
 - Each failure has an expected amount of lost data
 - Counting arguments for fraction of possible failures that lose data and how much



So How Big are Reliability Differences?

- Three copies more reliable
- Bigger systems less likely to have >2 blocks lost in any RAID set (8+2)/triple (3)
- Bigger systems repair in parallel faster (declustered)
- Triplication has ~3X disks for same user data, so ~3X faster failure & repair
- Delay in repairing is costly
- Assume .8TB/disk used, 64MB blocks, 1% AFR disk fail, exponential repair is either $12/N$ or $0.5+12/N$ (Markov model)



Closing

- The future is a world of failures everywhere
- We need tools to tame the raging beast
- Measure everything Know your rates
- Speak the unspeakable Loss happens
- Simple tools intuitive Educate always